## 2003, 2004 RULES OF ROBOTRACE

Robotrace is a competition in which robots run in a specified oval course to determine which is the fastest. Robots that enter robotrace races are called "robotracers".

## 1. Rul es for Robotr ace

1-1. Robot r acer s must be sel f- sust ai ned, and not exter nally oper at ed, by wire or by radio, except at the time of starting.
1-2. No addition, renoval, repl acement or change shal I be made t o the har dwar e or sof tware of a robot racer by the oper at or during a contest. It is however permissible to make minor repai $r$ s.

1-3. A Robot racer shall not exceed 25 cmin overall length, 25 cmin overall width and 20 cmin overall hei ght.
2. Rul es for the Course

2-1. The surface of a cour se shal l be pai nted in bl ack, and the circunference shall be i ndi cated by white lines, 1.9 cmin width.

2-2. A cour se shall be in the shape of an oval composed of straight Iines and arcs, its mini mum t ur ni ng radi us shal l be 15 cm

2-3. The radi us of curvat ure of $t$ he arc shal I be at I east 15 cm and $t$ he di st ance bet ween points of curvature variation shall be at least 15 cm

2-4. The total length of a course shal l be no more than 60 m at its circumference. A course may intersect (the angle of inter section shall be $90 \pm 5$ deg.) (See Fig. 3), however, robotracers shall not turn left or right at an intersection.
2-5. The startingline and the goal line are to be located in the straight section of the circuit, and the goal line is to be locat ed 100 cm behind the starting line. A starting marker and goal marker are to be affixed at the startingline and the goal line on the right si de pointing in the direction of the race. A starting gate and a goal gate shall be placed at the starting line and at the goal line, respectively. These gates shall be 40 cmin width and 25 cmin hei ght on the inside. The area between the gat es shall be called the "st art-goal area" (See Fig. 4, 5, 6).
2-6. The areas within 25 cm of the starting line and goal Iine are to be strai ght, and the areas within 25 cm bef ore and behind the inter section shall be straight.

2- 7. A corner marker shall be affixed on the left side in the direction of the race
(See Fig. 7) at each poi nt where the curvat ure of the course changes.
2-8. The circuit surface of a cour se shall be level as a rule, however, portions inclined
at a maxi mum of 5 degr ee may be i ncl uded.

## 3. Provi si on for Races

3-1. To time it takes for a robotracer to make the circuit of a cour se shall be recorded as the record Iap time of the robotracer.
3-2. After the course is di sclosed, the oper at or is not to feed any inf ormation on the course into the robotracer. In addition, the oper at or is not to revi se the cour se-rel at ed information or eliminate it partially by oper ating a switch, etc., during the contest.
3-3. To determine the I ap time of a robotracer, the period fromt he time when the sensor at the starting line detects part of the body of the robotracer to the time when the sensor at the goal line detects part of the body of the same robotracer shal l be cl ocked. However, no measured Iap time shall be regarded as a record unl ess the entire body of the robotracer passes through the goal line.
3.4. Each robotracer shall be provided with three minutes, and may run three times withinthis time limit.
3-5. Robotracers shall start within the defined start-goal area, and shall go in the specified direction. However, a series of runs may be made without interruption.
3. 6. Robotracers must aut omatically cone to a st op within the start/goal area, and remain there for at least two seconds after compl eting a run.
3. 7. A robotracer's run shall be deemed to end when the robotracer stops for more than 2 seconds or goes of $f$ the course during its run.
3. 8. The oper at or shall not touch a runni ng robot racer unl ess inst ruct ed to do so by the t our nament committ ee chair per son, or unl ess int ending to wi thdr aw the robot fromt he race and authorized to do so by the chai rper son. The tour nament committee chair person shall comply with a request to withdrawfromthe race onl $y$ when the robotracer becones unable to run.
3-9. If the body of a runni ng robotracer completely goes away fromthe lines, the robot $r$ acer shal l be consi der ed to have gone of $f$ the course.

3-10. The I ighting, temper at ure and humidity of circuits shall be the same sa those of or di nary indoor envi ronments. No request to adj ust the I ighting shal I be complied with. 3-11. The tour nament committee chai rper son may denand fromoper at ors such expl anation concerning their robotracers as he / she deens necessary. The chai rper son may direct oper at or s to give up racing, di squalify them and take any other necessary measures at his/her di scretion.
[ Not es]
(1) Loadi ng a program or changing a ROM during a tournament is not permitted. It is al so prohi bited to connect a robotracer to any new y devel oped device or console box, separate fromthe body, to give instructions rel at ed to the execution of prograns.
(2) If, after the starting procedures, the robotracer comes to a stop or goes of $f$ the course and does not reach the starting Iine, the robot shall be consi der ed to have nade a run.
(3) Even if a robotracer comples each run and crosses the goal iine, if it does not aut omatically stop within the start/goal area, its run will be deened invalid.
(4) A course may have arcs with different curvatures Iinked continuously. (See Fig. 7)
(5) Differences in level of 1 mm or so may be formed in courses.
(6) The sensors at the start line and the goal line (illustrated in Fig. 5) shall be of the penetrating infrared type, with the optical axis horizontal and positioned approx. 1cm above the circuit surface.
(7) Complaints about the grip on the floor surface will not be accepted.

Fig. of Robotrace Contest Rule


Fig. A • start - goal area


The anale of intersection strall be $90 \pm 5 \mathrm{deg}$ Fia3 - Intersection

(sart ind line and goal line is rotd reved)
Fig.6 - start me rher and goal ma ther


Fig. of Robotrace Contest Junior Rule


